

Optimized High Order Explicit Runge-Kutta-Nyström Schemes

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Bibliography and motivation

- Runge-Kutta-Nyström methods well adapted to solve $y'' = f(t, y)$
- Proposed methods (by [Hairer](#), [Dormand Prince](#), etc) have been optimized for **non-stiff** problems
- Stability condition (CFL) optimized by [Chawla and Sharma](#) for order **3, 4, 5**
- Numerical optimization for orders **6, 7, 8 and 10**
- Application to **stiff** problems (non-linear Maxwell's equations)

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Runge-Kutta Nyström schemes

- One-step schemes that solve $y'' = f(t, y)$
- y_{n+1} and y'_{n+1} are computed from y_n and y'_n .
- Defined through coefficients c_i, b_i, \bar{b}_i and $\bar{a}_{i,j}$, that must satisfy order conditions to obtain a scheme of order p
- If a Runge-Kutta scheme is known, a Runge-Kutta-Nyström (RKN) scheme can be obtained by setting $\bar{A} = A^2, \bar{b} = A^T b$

Runge-Kutta Nyström schemes

Initial conditions : y_0, y'_0

$$\left\{ \begin{array}{l} k_j = f\left(t_n + c_j \Delta t, y_n + c_j \Delta t y'_n + \Delta t^2 \sum_j \bar{a}_{i,j} k_j\right) \\ y_{n+1} = y_n + \Delta t y'_n + \Delta t^2 \sum_j \bar{b}_j k_j \\ y'_{n+1} = y'_n + \Delta t \sum_j b_j k_j \end{array} \right.$$

Second-order scheme ($p=2$)

Order conditions to satisfy to obtain a second-order scheme:

$$\sum_i b_i = 1, \quad \sum_i b_i c_i = \frac{1}{2}, \quad \sum_i \bar{b}_i = \frac{1}{2}$$

A one-stage scheme satisfies these conditions:

$$\bar{A} = (0), \quad c = \left(\frac{1}{2}\right), \quad b = (1), \quad \bar{b} = \left(\frac{1}{2}\right)$$

Second-order scheme (p=2)

$$\begin{cases} k_0 = f\left(t_n + \frac{\Delta t}{2}, y_n + \frac{\Delta t}{2} y'_n\right) \\ y_{n+1} = y_n + \Delta t y'_n + \frac{\Delta t^2}{2} k_0 \\ y'_{n+1} = y'_n + \Delta t k_0 \end{cases}$$

- Conservative scheme
- Stability condition : $\Delta t \leq \frac{2}{\sqrt{\|A\|_2}}$ (for f linear and replaced by a matrix A)

Second-order scheme (p=2)

Compared to the usual second-order two-step scheme:

$$\frac{y_{n+1} - 2y_n + y_{n-1}}{\Delta t^2} = f(t_n, y_n)$$

Similar properties:

⇒ Conservative scheme

⇒ Same stability condition : $\Delta t \leq \frac{2}{\sqrt{\|A\|_2}}$

⇒ these two schemes are optimal with respect to this stability condition

Stability condition

Linear case : $f(t, y) = Ay$

\hat{A} being the symbol of A (an eigenvalue), we have:

$$\begin{bmatrix} y_{n+1} \\ w_{n+1} \end{bmatrix} = D(\Delta t^2 \hat{A}) \begin{bmatrix} y_n \\ w_n \end{bmatrix}$$

Let us note

$$z = \Delta t^2 \hat{A}$$

$D(z)$ is a 2x2 matrix whose entries are polynomials in z , the coefficients of the polynomials depend on b_i, c_i, \bar{b}_i and $\bar{a}_{i,j}$.

Matrix $D(z)$ for order 2

$$D(z) = \begin{pmatrix} 1 + \frac{z}{2} & z + \frac{z^2}{4} \\ 1 & 1 + \frac{z}{2} \end{pmatrix}$$

Stability condition

Matrix $D(z)$ for order 3

$$D(z) = \begin{pmatrix} 1 + \frac{z}{2} + \beta_0 z^2 & z + \frac{z^2}{6} + \beta_1 z^3 \\ 1 + \frac{z}{6} & 1 + \frac{z}{2} + \beta_2 z^2 \end{pmatrix}$$

Coefficients β_i depend on b_i , c_i , \bar{b}_i and $\bar{a}_{i,j}$

Stability condition

Matrix $D(z)$ for order 4

$$D(z) = \begin{pmatrix} 1 + \frac{z}{2} + \frac{z^2}{24} + \beta_0 z^3 & z + \frac{z^2}{6} + \beta_1 z^3 + \beta_2 z^4 \\ 1 + \frac{z}{6} + \beta_3 z^2 & 1 + \frac{z}{2} + \frac{z^2}{24} + \beta_4 z^3 \end{pmatrix}$$

Coefficients β_i depend on b_i , c_i , \bar{b}_i and $\bar{a}_{i,j}$

Stability condition

Matrix $D(z)$ for order 5

$$D(z) = \begin{pmatrix} 1 + \frac{z}{2} + \frac{z^2}{24} + \beta_0 z^3 + \beta_1 z^4 & z + \frac{z^2}{6} + \frac{z^3}{120} + \beta_2 z^4 + \beta_3 z^5 \\ 1 + \frac{z}{6} + \frac{z^2}{120} + \beta_4 z^3 & 1 + \frac{z}{2} + \frac{z^2}{24} + \beta_5 z^3 + \beta_6 z^4 \end{pmatrix}$$

\Rightarrow Taylor expansion of $\cos(\sqrt{-z})$ and $\sin(\sqrt{-z})$

Stability condition

Amplification factor

$$G(z) = \text{Spectral radius of } D(z)$$

CFL number is defined as the first time when $G(z) > 1$:

$$\text{CFL number} = \min_{z \leq 0} \{ \sqrt{-z} \text{ such that } G(z) > 1 \}$$

Stability condition is then given as:

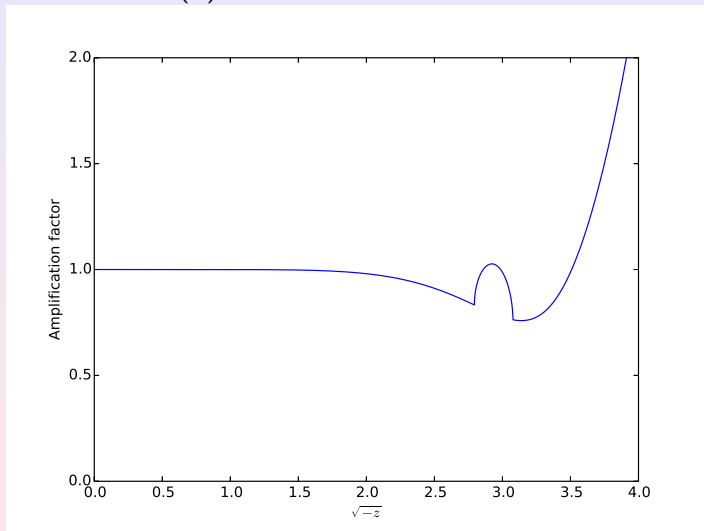
$$\Delta t \leq \frac{\text{CFL number}}{\sqrt{\|A\|_2}}$$

For $p = 2$, we have obtained

$$\text{CFL number} = 2$$

Numerical computation of the CFL

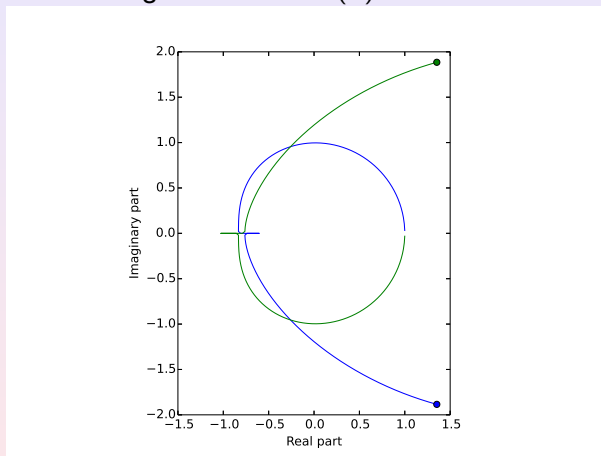
Amplification factor $G(z)$ versus $\sqrt{-z}$ for a 6-th order RKN scheme



Presence of a local maximum

Numerical computation of the CFL

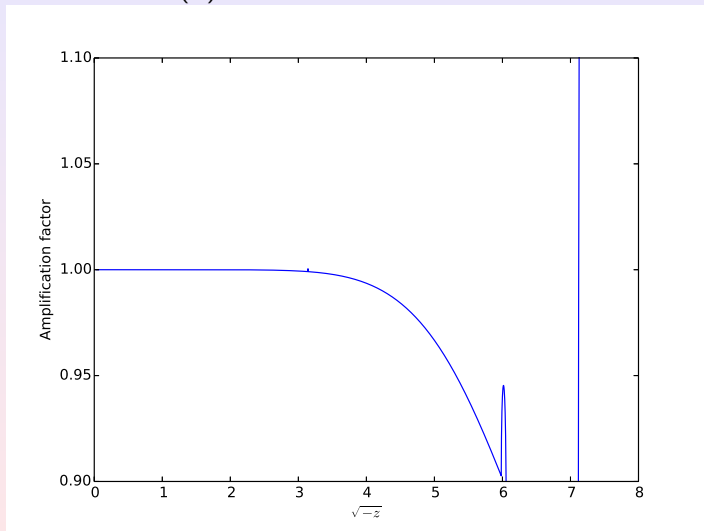
Trajectory of the two eigenvalues of $D(z)$



The local maximum occurs when the two eigenvalues of $D(z)$ are real

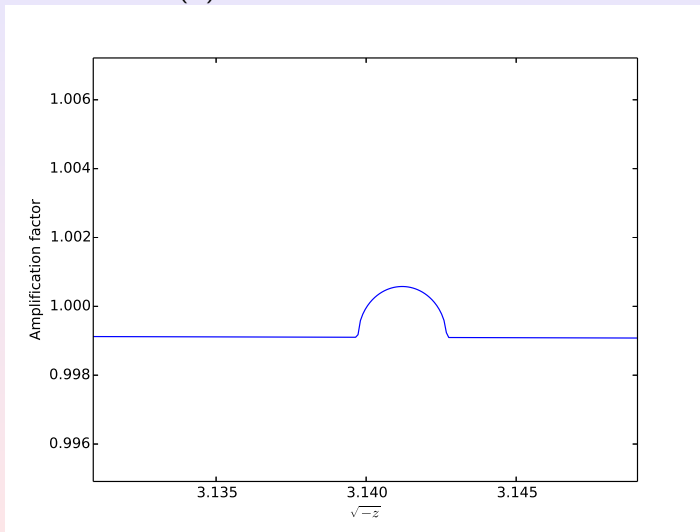
Numerical computation of the CFL

Amplification factor $G(z)$ versus $\sqrt{-z}$ for a 7-th order RKN scheme



Numerical computation of the CFL

Amplification factor $G(z)$ versus $\sqrt{-z}$ for a 7-th order RKN scheme



Numerical computation of the CFL

Main elements of the algorithm used to compute the CFL:

- Check that $G(-10^{-5}) \leq 1$
- Decrease z by a variable step size Δz_k to capture the intersection of eigenvalues
- Compute a local maximum if we find z such that $G(z) > \max(G(z - \Delta z_k), G(z + \Delta z_{k-1}))$
- The final CFL number is found by bisection method when we have found z_0 and z_1 such that $G(z_0) \leq 1$ and $G(z_1) > 1$

Optimization with a minimal number of stages

- For order 3, 4, 5, 6, 7, 8, we are optimizing the families proposed in *Méthodes de Nyström pour l'équation différentielle $y'' = f(x, y)$* , E. Hairer
- For order 10, we are optimizing the family proposed in *A one-step method of order 10 for $y'' = f(x, y)$* , E. Hairer
- These families achieve the desired order with a minimal number of stages
- A large number of values for free parameters are tested, an optimization (the simplex method by Nelder and Mead) is performed for the best candidates

Order 3 (two stages)

$$c_0 = \alpha, \quad c_1 = \frac{2 - 3\alpha}{3 - 6\alpha}$$

$$b_0 = \frac{\frac{c_1}{2} - \frac{1}{3}}{c_0(c_1 - c_0)}, \quad b_1 = 1 - b_0$$

$$\bar{b}_0 = \frac{\frac{c_1}{2} - \frac{1}{6}}{c_1 - c_0}, \quad \bar{b}_1 = \frac{1}{2} - \bar{b}_0$$

$$\bar{a}_{1,0} = \frac{1}{6b_1}$$

Order 3 (two stages)

α is a free parameter

$$c_0 = \alpha, \quad c_1 = \frac{2 - 3\alpha}{3 - 6\alpha}$$

An optimal CFL of 2.498 is obtained for

$$\alpha = \frac{3 - \sqrt{3}}{6}$$

Order 4 (three stages)

$$c_0 = \alpha, \quad c_1 = \frac{1}{2}, \quad c_2 = 1 - \alpha$$

$$b_0 = \frac{1}{6(1 - 2\alpha)^2}, \quad b_1 = 1 - 2b_0, \quad b_2 = b_0$$

$$\bar{b}_0 = b_0(1 - c_0), \quad \bar{b}_1 = b_1(1 - c_1), \quad \bar{b}_2 = b_2(1 - c_2)$$

$$\bar{a}_{1,0} = \frac{(1 - 4\alpha)(1 - 2\alpha)}{8(6\alpha(\alpha - 1) + 1)},$$

$$\bar{a}_{2,0} = 2\alpha(1 - 2\alpha), \quad \bar{a}_{2,1} = \frac{(1 - 2\alpha)(1 - 4\alpha)}{2}$$

Order 4 (three stages)

α is a free parameter

$$c_0 = \alpha, \quad c_1 = \frac{1}{2}, \quad c_2 = 1 - \alpha$$

An optimal CFL of 3.939 is obtained for

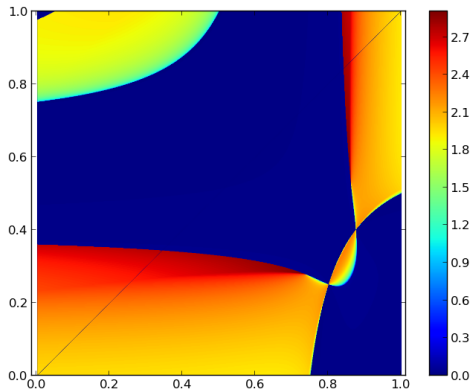
$$\alpha = \frac{1}{4 \left(1 + \cos\left(\frac{\pi}{9}\right)\right)}$$

Order 5 (four stages)

α and β are free parameters

$$c_0 = 0, \quad c_1 = \alpha, \quad c_3 = \beta, \quad c_2 = \frac{12 - 15(\alpha + \beta) + 20\alpha\beta}{15 - 20(\alpha + \beta) + 30\alpha\beta}$$

CFL number versus these two parameters:



Order 5 (four stages)

α and β are free parameters

$$c_0 = 0, \quad c_1 = \alpha, \quad c_3 = \beta, \quad c_2 = \frac{12 - 15(\alpha + \beta) + 20\alpha\beta}{15 - 20(\alpha + \beta) + 30\alpha\beta}$$

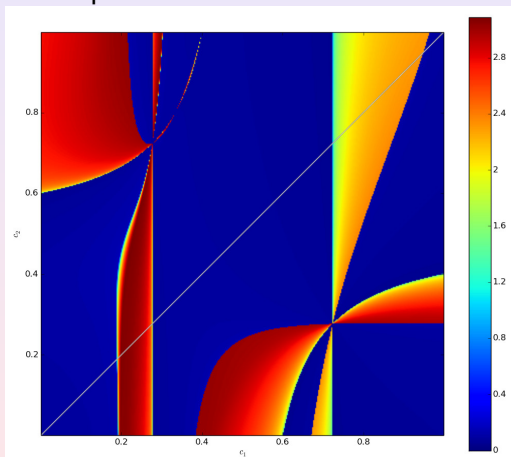
An optimal CFL of 2.908 is obtained for

$$\alpha = \frac{4}{11 - \sqrt{16\sqrt{10} - 39}},$$

$$\beta = \frac{165\alpha^2 - 195\alpha + 50 + \sqrt{5(45\alpha^4 + 90\alpha^3 - 105\alpha^2 + 36\alpha - 4)}}{225\alpha^2 - 240\alpha + 60}$$

Order 6 (5 stages)

c_1 and c_2 are free parameters
CFL number vs these parameters:



Order 6 (5 stages)

c_1 and c_2 are free parameters

$$c_0 = 0, \quad c_4 = 1$$

$$c_3 = \frac{\frac{1}{30} - \frac{1}{20}(c_1 + c_2) + \frac{1}{12}c_1c_2}{\frac{1}{20} - \frac{1}{12}(c_1 + c_2) + \frac{1}{6}c_1c_2}.$$

An optimal CFL of 3.089 is obtained for

$$c_1 \approx 0.22918326, \quad c_2 \approx 0.5$$

Order 7 (7 stages)

$\alpha_0, \alpha_1, \alpha_2, \alpha_3$ are four free parameters

$$c_0 = 0, \quad c_1 = \alpha_0, \quad c_2 = \alpha_1, \quad c_3 = \alpha_2, \quad c_4 = \alpha_3$$

$$c_5 = \frac{-\frac{1}{7} + \frac{\sigma_1^c}{6} - \frac{\sigma_2^c}{5} + \frac{\sigma_3^c}{4} - \frac{\sigma_4^c}{3}}{-\frac{1}{6} + \frac{\sigma_1^c}{5} - \frac{\sigma_2^c}{4} + \frac{\sigma_3^c}{3} - \frac{\sigma_4^c}{2}}, \quad c_6 = 1$$

An optimal CFL of 7.0875 is obtained for:

$$\alpha_0 = 0.110451398065702, \quad \alpha_1 = 0.173816271367107$$

$$\alpha_2 = 0.459433163929695, \quad \alpha_3 = 0.652002232653235$$

Order 8 (8 stages)

$\alpha_0, \alpha_1, \alpha_2, \alpha_3$ are four free parameters

$$c_0 = 0, \quad c_1 = \frac{\alpha_0}{2}, \quad c_2 = \alpha_0, \quad c_3 = \alpha_1, \quad c_4 = \alpha_2, \quad c_5 = \alpha_3$$

$$c_6 = \frac{-\frac{1}{8} + \frac{\sigma_1^c}{7} - \frac{\sigma_2^c}{6} + \frac{\sigma_3^c}{5} - \frac{\sigma_4^c}{4} + \frac{\sigma_5^c}{3}}{-\frac{1}{7} + \frac{\sigma_1^c}{6} - \frac{\sigma_2^c}{5} + \frac{\sigma_3^c}{4} - \frac{\sigma_4^c}{3} + \frac{\sigma_5^c}{2}}, \quad c_7 = 1$$

An optimal CFL of 7.8525 is obtained for:

$$\alpha_0 = 0.135294127286225, \quad \alpha_1 = 0.24015308384744$$

$$\alpha_2 = 0.453046953126355, \quad \alpha_3 = 0.695039606659698$$

Order 10 (11 stages)

There are four free parameters (b_1, b_3, b_4, r_5) and a permutation. r_5 defined as

$$\sum_{i=1}^{s-1} b_i c_i^k \sum_{j=1}^{i-1} \bar{a}_{i,j} c_j^5 = r_5$$

Gauss-Lobatto nodes defined as:

$$\left\{ \begin{array}{l} \gamma_1 = \frac{1}{2} \left(1 - \sqrt{\frac{7 + 2\sqrt{7}}{21}} \right), \quad \gamma_4 = 1 - \gamma_1 \\ \gamma_2 = \frac{1}{2} \left(1 - \sqrt{\frac{7 - 2\sqrt{7}}{21}} \right), \quad \gamma_3 = 1 - \gamma_2 \end{array} \right.$$

c_4, c_5, c_6, c_7 to choose among these four Gauss-Lobatto nodes (24 permutations possible)

Order 10 (11 stages)

There are four free parameters (b_1, b_3, b_4, r_5) and a permutation.
An optimal CFL of 4.7527 is obtained for

$$(c_4, c_5, c_6, c_7) = (\gamma_4, \gamma_3, \gamma_1, \gamma_2).$$

$$r_5 = 0.0021632268153138$$

and does not depend on b_1, b_3, b_4 that can be chosen as:

$$b_1 = 0, \quad b_3 = -0.1, \quad b_4 = 0$$

Efficiency of the optimized schemes

s being the number of stages, the efficiency is given as:

$$\text{Efficiency} = \frac{\text{CFL number}}{2s}$$

Efficiency obtained for the different orders:

Order	2	3	4
Efficiency	100 %	62.5 %	65.7 %

Order	5	6	7	8	10
Efficiency	36.4 %	30.9 %	50.6 %	49.1 %	21.6 %

Non-linear Maxwell's equations

$$\left\{ \begin{array}{l} \frac{\epsilon_\infty}{c^2} \frac{\partial^2 \mathbf{E}}{\partial t^2} + \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \left(\sum_k \mathbf{P}_k \right) + \text{curl}(\text{curl} \mathbf{E}) + \frac{\gamma}{c^2} \frac{\partial^2}{\partial t^2} (|\mathbf{E}|^2 \mathbf{E}) = 0 \\ \frac{1}{\omega_k^2} \frac{\partial^2 \mathbf{P}_k}{\partial t^2} + \mathbf{P}_k = \alpha_k \mathbf{E} \\ \mathbf{E}(x, y, z, t = 0) = \frac{\partial \mathbf{E}}{\partial t}(x, y, z, t = 0) = 0 \\ \mathbf{E}(x, y, z = 0, t) = \text{Given impulsion} \end{array} \right.$$

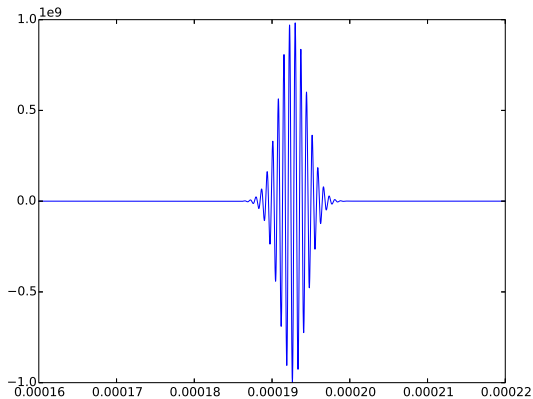
$\epsilon_\infty, c, \gamma, \alpha_k, \omega_k$ physical constants (silica is chosen)

Simulation parameters

- 1-D finite elements Q_{10}
- Domain $[0, 1.5 \cdot 10^{-4}]$ (more than 200 wavelengths) with 250 cells
- Circular polarization, $\lambda_0 = 1.053 \mu m$
- Optical period $T_0 = 3.5 \cdot 10^{-15} s$
- Final time $T_{\max} = 5 \cdot 10^{-11} s$
- Gaussian impulsion of width $60 \cdot 10^{-15} s$

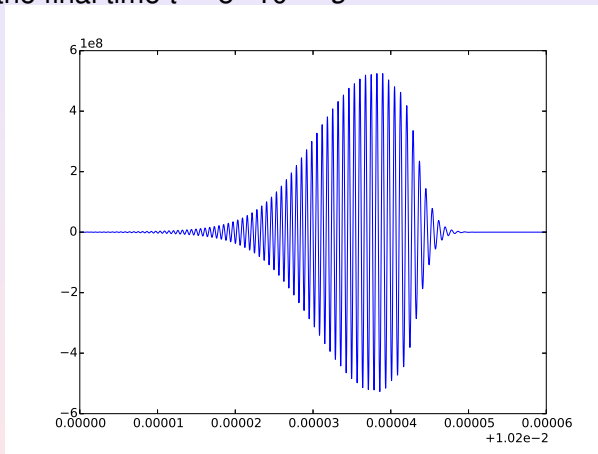
Simulation parameters

Solution at $t = 10^{-12}$ s



Simulation parameters

Solution at the final time $t = 5 \cdot 10^{-11} \text{ s}$



Numerical results

Computation time needed to reach an error of 1 % :

Order	2	3	4	5	6	7	8	10
Time	1 240 s	186s	41s	54s	63s	44s	47s	106s

For orders ≥ 5 , the error is below 10^{-5} , the CFL is reached.

Numerical results

Computation time needed to reach an error of 10^{-4} :

Order	2	3	4	5	6	7	8	10
Time	14 164s	647s	129s	54s	63s	44s	47s	106s

For orders ≥ 5 , the error is below 10^{-5} , the CFL is reached.

- Optimization with additional stages
- Continuous interpolants

Thanks for your attention