

On the hydrodynamic description of aerosols

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Modelling of aerosols : fluid-kinetic couplings



“An aerosol is a suspension of fine solid particles or liquid droplets in air or another gas.” Hinds, *Aerosol Technology*, 1999.

Modelling of aerosols : fluid-kinetic couplings



- **Suspension** : kinetic description by a **distribution function** $f(t, x, v)$, giving the continuous distribution of particles with position x and velocity v at time t .
- **Fluid** : viscous, incompressible, homogeneous, described by velocity $u(t, x)$ and pressure $p(t, x)$.

Coupling of equations of **fluid mechanics** with **kinetic equations** [O'Rourke 1981].

Modelling of aerosols : fluid-kinetic couplings



Question : how relevant is it to describe aerosols only by hydrodynamic equations ?

The Vlasov-Navier-Stokes system for $(x, v) \in \mathbb{T}^3 \times \mathbb{R}^3$

$$\begin{cases} \partial_t u + u \cdot \nabla_x u - \Delta_x u + \nabla_x p = - \int_{\mathbb{R}^3} (u - v) f \, dv, \\ \operatorname{div}_x u = 0, \\ \partial_t f + v \cdot \nabla_x f + \nabla_v \cdot (f(u - v)) = 0, \\ f|_{t=0} = f_0, \quad u|_{t=0} = u_0. \end{cases}$$

- **Forcing** in Navier-Stokes : **Brinkman force**
- **Force** in the Vlasov equation : **drag force**
- Moments in velocity

$$\rho_f(t, x) = \int_{\mathbb{R}^3} f(t, x, v) \, dv,$$

Density of particles

$$j_f(t, x) = \int_{\mathbb{R}^3} f(t, x, v) v \, dv$$

Momentum of particles.

The Vlasov-Navier-Stokes system for $(x, v) \in \mathbb{T}^3 \times \mathbb{R}^3$

$$\begin{cases} \partial_t u + u \cdot \nabla_x u - \Delta_x u + \nabla_x p = -\rho_f u + j_f, \\ \operatorname{div}_x u = 0, \\ \partial_t f + v \cdot \nabla_x f + \nabla_v \cdot (f(u - v)) = 0, \\ f|_{t=0} = f_0, \quad u|_{t=0} = u_0. \end{cases}$$

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Momentum of particles.

The Vlasov-Navier-Stokes system : formal properties

- **Characteristic** curves for Vlasov :

$$\begin{cases} \frac{d}{ds} X_{s,t}(x, v) = V_{s,t}(x, v), & X_{t,t}(x, v) = x, \\ \frac{d}{ds} V_{s,t}(x, v) = u(s, X_{s,t}(x, v)) - V_{s,t}(x, v), & V_{t,t}(x, v) = v. \end{cases}$$

We have

$$f(t, x, v) = e^{3t} f_0(X_{0,t}(x, v), V_{0,t}(x, v)).$$

- **A priori estimates for Vlasov** :

$$f_0 \geq 0 \implies \forall t \geq 0, f(t) \geq 0,$$

$$\|f(t)\|_{L^1(\mathbb{T}^3 \times \mathbb{R}^3)} = \|f_0\|_{L^1(\mathbb{T}^3 \times \mathbb{R}^3)},$$

$$\|f(t)\|_{L^\infty(\mathbb{T}^3 \times \mathbb{R}^3)} = e^{3t} \|f_0\|_{L^\infty(\mathbb{T}^3 \times \mathbb{R}^3)}.$$

The Vlasov-Navier-Stokes system : formal properties

- **Energy-dissipation** identity :

$$E(t) = \frac{1}{2} \int_{\mathbb{T}^3} |u(t, x)|^2 dx + \frac{1}{2} \int_{\mathbb{T}^3 \times \mathbb{R}^3} f(t, x, v) |v|^2 dv dx,$$

$$D(t) = \int_{\mathbb{T}^3} |\nabla u(t, x)|^2 dx + \int_{\mathbb{T}^3 \times \mathbb{R}^3} f(t, x, v) |u(t, x) - v|^2 dv dx,$$

we have formally

$$\frac{d}{dt} E(t) + D(t) = 0.$$

When $f \equiv 0$, this is nothing but the usual energy-dissipation law for incompressible Navier-Stokes.

The Vlasov-Navier-Stokes system : Leray solutions

Theorem (Boudin, Desvillettes, Grandmont, Moussa (2009))

Given $f_0 \geq 0$ in $L^1 \cap L^\infty(\mathbb{T}^3 \times \mathbb{R}^3)$ and $u_0 \in L^2(\mathbb{T}^3)$ with $E(0) < +\infty$, there exists a **global weak solution** $(u(t), f(t))$ to the Vlasov-Navier-Stokes system that satisfies the energy-dissipation inequality

$$E(t) + \int_s^t D(\tau) d\tau \leq E(s)$$

for $s = 0$ and almost all $s \geq 0$, and all $t \geq s$.

We call such solutions **Leray solutions**.

High field limit of the Vlasov-Navier-Stokes system

We shall focus on the following limit $\varepsilon \rightarrow 0$ for the Vlasov-Navier-Stokes system :

$$\left\{ \begin{array}{l} \partial_t u_\varepsilon + u_\varepsilon \cdot \nabla_x u_\varepsilon - \Delta_x u_\varepsilon + \nabla_x p_\varepsilon = \frac{1}{\varepsilon} (-\rho_{f_\varepsilon} u_\varepsilon + j_{f_\varepsilon}), \\ \operatorname{div}_x u_\varepsilon = 0, \\ \partial_t f_\varepsilon + v \cdot \nabla_x f_\varepsilon + \frac{1}{\varepsilon} \nabla_v \cdot (f_\varepsilon (u_\varepsilon - v)) = 0, \\ f_\varepsilon|_{t=0} = f_{0,\varepsilon}, \quad u_\varepsilon|_{t=0} = u_{0,\varepsilon}. \end{array} \right.$$

This corresponds to the regime where

- The Stokes relaxation time is small compared to the observation time ;
- The particles are small compared to the observation length.

Question : what can we say about the behavior of $(u_\varepsilon, f_\varepsilon)$ when $\varepsilon \rightarrow 0$?

Formal limit 1/2

- Scaled energy and dissipation :

$$E_\varepsilon(t) = \frac{1}{2} \int_{\mathbb{T}^3} |u_\varepsilon(t, x)|^2 dx + \frac{1}{2} \int_{\mathbb{T}^3 \times \mathbb{R}^3} f_\varepsilon(t, x, v) |v|^2 dv dx,$$

$$D_\varepsilon(t) = \int_{\mathbb{T}^3} |\nabla u_\varepsilon(t, x)|^2 dx + \frac{1}{\varepsilon} \int_{\mathbb{T}^3 \times \mathbb{R}^3} f_\varepsilon(t, x, v) |u_\varepsilon(t, x) - v|^2 dv dx,$$

- Assume $(\rho_{f_\varepsilon}, u_\varepsilon) \rightharpoonup (\rho, u)$. By the energy–dissipation identity

$$\frac{d}{dt} E_\varepsilon(t) + D_\varepsilon(t) = 0,$$

we expect

$$\int_0^{+\infty} \int_{\mathbb{T}^3 \times \mathbb{R}^3} f_\varepsilon(t, x, v) |u_\varepsilon(t, x) - v|^2 dv dx dt \xrightarrow{\varepsilon \rightarrow 0} 0,$$

which formally implies

$$f_\varepsilon \xrightarrow{\varepsilon \rightarrow 0} \rho \otimes \delta_{v=u}.$$

Formal limit 2/2

- Conservation of mass ($\rho_{f_\varepsilon} = \int_{\mathbb{R}^3} f_\varepsilon dv$) and momentum ($j_{f_\varepsilon} = \int_{\mathbb{R}^3} f_\varepsilon v dv$) for Vlasov :

$$\begin{cases} \partial_t \rho_{f_\varepsilon} + \operatorname{div}_x j_{f_\varepsilon} = 0, \\ \partial_t j_{f_\varepsilon} + \operatorname{div}_x \left(\int_{\mathbb{R}^3} f_\varepsilon v \otimes v dv \right) = -F_\varepsilon, \end{cases}$$

with $F_\varepsilon = \frac{1}{\varepsilon} (-\rho_{f_\varepsilon} u_\varepsilon + j_{f_\varepsilon})$.

- Assuming furthermore that $F_\varepsilon \rightharpoonup_{\varepsilon \rightarrow 0} F$ and since $f_\varepsilon \rightharpoonup_{\varepsilon \rightarrow 0} \rho \otimes \delta_{v=u}$,

$$\begin{cases} \partial_t \rho + \operatorname{div}_x(\rho u) = 0, \\ \partial_t(\rho u) + \operatorname{div}_x(\rho u \otimes u) = -F. \end{cases}$$

- We can also pass to the limit in the Navier-Stokes equations :

$$\partial_t u + \operatorname{div}_x(u \otimes u) - \Delta_x u + \nabla_x p = F, \quad \operatorname{div}_x u = 0.$$

- Hence $(1 + \rho, u)$ must satisfy the **inhomogeneous incompressible Navier-Stokes** equations

$$\begin{cases} \partial_t \rho + \operatorname{div}_x(\rho u) = 0, \\ \partial_t((1 + \rho)u) + \operatorname{div}_x((1 + \rho)u \otimes u) - \Delta_x u + \nabla_x p = 0, \\ \operatorname{div}_x u = 0. \end{cases}$$

Formal limit 2/2



Main result

Theorem (DHK, D. Michel (2021+))

Assume $f_{0,\varepsilon} \geq 0 \in L^1 \cap L^\infty$ is decaying fast with respect to v and that $u_{0,\varepsilon}$ is (a bit) smooth (uniformly in ε).

- Assume $\sup_{\varepsilon \in (0,1)} \|f_{0,\varepsilon}\|_{L^1_v(\mathbb{R}^3; L^\infty_x(\mathbb{T}^3))} \ll 1$ and for some $r > 3$,

$$\int_{\mathbb{T}^3 \times \mathbb{R}^3} f_{0,\varepsilon} |v - u_{0,\varepsilon}|^r dv dx \lesssim \varepsilon^{r-1},$$

then there exists $T > 0$ such that, for all $t \in [0, T]$,

$$\|u_\varepsilon(t) - u(t)\|_{L^2(\mathbb{T}^3)} \xrightarrow{\varepsilon \rightarrow 0} 0, \quad W_1(f_\varepsilon(t), \rho \otimes \delta_{v=u}) \xrightarrow{\varepsilon \rightarrow 0} 0,$$

where $(1 + \rho, u)$ satisfies the inhomogeneous incompressible Navier-Stokes equations.

- Assume in addition that $\sup_{\varepsilon \in (0,1)} \|u_{0,\varepsilon}\|_{\dot{H}^{1/2}} \ll 1$ and that we are in a close to equilibrium regime, the convergences hold for all $T > 0$.

Vlasov-Fokker-Planck-Navier-Stokes

- [Goudon, Jabin, Vasseur 2004] previously studied the same regime for

$$\begin{cases} \partial_t u_\varepsilon + u_\varepsilon \cdot \nabla u_\varepsilon - \Delta u_\varepsilon + \nabla p_\varepsilon = \frac{1}{\varepsilon} (-\rho_{f_\varepsilon} u_\varepsilon + j_{f_\varepsilon}), \\ \operatorname{div} u_\varepsilon = 0, \\ \partial_t f_\varepsilon + v \cdot \nabla_x f_\varepsilon + \frac{1}{\varepsilon} (\nabla_v \cdot (f_\varepsilon (u_\varepsilon - v))) + \Delta_v f_\varepsilon = 0, \end{cases}$$

also deriving inhomogeneous incompressible Navier-Stokes in the limit $\varepsilon \rightarrow 0$.

- **Relative entropy** method ([Brenier 2000] [Golse 2000]) :

$$\mathcal{H}_\varepsilon(t) = \int_{\mathbb{T}^3 \times \mathbb{R}^3} (f_\varepsilon \log(f_\varepsilon / \mathcal{M}_{\rho, u}) + \mathcal{M}_{\rho, u} - f_\varepsilon) dv dx + \frac{1}{2} \int_{\mathbb{T}^3} |u_\varepsilon - u|^2 dx.$$

The limit object for VFPNS is the **local Maxwellian**

$$\mathcal{M}_{\rho, u}(t, x, v) = \frac{\rho(t, x)}{(2\pi)^{3/2}} \exp(-|v - u(t, x)|^2 / 2),$$

- Key fact :

$$\mathcal{H}_\varepsilon(t) \leq \mathcal{H}_\varepsilon(0) + \int_0^t \mathcal{H}_\varepsilon(s) ds + \sqrt{\varepsilon}.$$

Relative entropy estimates

- **Relative entropy** for Vlasov-Navier-Stokes :

$$\mathcal{H}_\varepsilon(t) = \frac{1}{2} \int_{\mathbb{T}^3 \times \mathbb{R}^3} f_\varepsilon |v - u|^2 dv dx + \frac{1}{2} \int_{\mathbb{T}^3} |u_\varepsilon - u|^2 dx.$$

- There holds

$$\begin{aligned} \mathcal{H}_\varepsilon(t) + \int_0^t \int_{\mathbb{T}^3} |\nabla_x(u_\varepsilon - u)|^2 dx ds + \frac{1}{\varepsilon} \int_0^t \int_{\mathbb{T}^3 \times \mathbb{R}^3} |v - u_\varepsilon|^2 f_\varepsilon dv dx ds \\ \leq \mathcal{H}_\varepsilon(0) + \int_0^t \sum_{j=1}^4 I_j ds. \end{aligned}$$

$$I_1 := - \int_{\mathbb{T}^3 \times \mathbb{R}^3} f_\varepsilon (v - u) \otimes (v - u) : \nabla_x u dv dx,$$

$$I_2 := - \int_{\mathbb{R}^3} (u_\varepsilon - u) \otimes (u_\varepsilon - u) : \nabla_x u dx, \quad I_3 := \int_{\mathbb{T}^3 \times \mathbb{R}^3} f_\varepsilon (v - u_\varepsilon) \cdot G dv dx,$$

$$I_4 := \int_{\mathbb{T}^3} (\rho_{f_\varepsilon} - \rho)(u_\varepsilon - u) \cdot G dx, \quad G := \frac{\nabla_x p - \Delta_x u}{1 + \rho}.$$

A conditional \dot{H}^{-1} estimate

The problematic term is I_4 :

$$\begin{aligned} |I_4| &= \left| \int_{\mathbb{T}^3} (\rho_{f_\varepsilon} - \rho)(u_\varepsilon - u) \cdot G \, dx \right| \\ &\lesssim \|\rho_{f_\varepsilon} - \rho\|_{\dot{H}^{-1}(\mathbb{T}^3)} \|\nabla_x(u_\varepsilon - u)\|_{L^2(\mathbb{T}^3)} \end{aligned}$$

Lemma

Let $T > 0$. Assume there exists $C > 0$ such that

$$\sup_{\varepsilon \in (0,1)} \|\rho_{f_\varepsilon}\|_{L^\infty(0,T \times \mathbb{T}^3)} \leq C.$$

Then for all $t \in (0, T)$,

$$\begin{aligned} \|\rho_{f_\varepsilon}(t) - \rho(t)\|_{\dot{H}^{-1}(\mathbb{T}^3)} &\lesssim \|\rho_{f_{\varepsilon,0}} - \rho(0)\|_{\dot{H}^{-1}(\mathbb{T}^3)} \\ &\quad + \int_0^t \|(j_{f,\varepsilon} - \rho_{f,\varepsilon})u\|_{L^2(\mathbb{T}^3)} \, ds + \int_0^t \|u_\varepsilon - u\|_{L^2(\mathbb{T}^3)} \, ds. \end{aligned}$$

The key is thus the **uniform L^∞ control of ρ_{f_ε}** .

Towards a control of ρ_{f_ε}

The conservation laws of the equations seem not enough to ensure such a control. However, by the method of characteristics

$$\rho_{f_\varepsilon}(t, x) = e^{\frac{3t}{\varepsilon}} \int_{\mathbb{R}^3} f_{0,\varepsilon}(X_{0,t}^\varepsilon(x, v), V_{0,t}^\varepsilon(x, v)) dv.$$

When $\int_0^T \|\nabla_x u_\varepsilon(s)\|_{L^\infty(\mathbb{T}^3)} ds \ll 1$, the map $v \mapsto V_{0,t}^\varepsilon(x, v)$ is a \mathcal{C}^1 diffeomorphism and

$$|\det D_v V_{0,t}^\varepsilon(x, v)| \geq e^{\frac{3t}{\varepsilon}}/4.$$

Lemma

There is $\delta > 0$ such that, if for $T > 0$

$$\sup_{\varepsilon \in (0,1)} \int_0^T \|\nabla_x u_\varepsilon(s)\|_{L^\infty(\mathbb{T}^3)} ds \leq \delta$$

then

$$\sup_{\varepsilon \in (0,1)} \|\rho_{f_\varepsilon}\|_{L^\infty((0,T) \times \mathbb{T}^3)} \lesssim 1.$$

Modulated energy

Following [Choi, Kwon 2015] we introduce the **modulated energy**

$$\mathcal{E}_\varepsilon(t) = \frac{1}{2} \int_{\mathbb{T}^3 \times \mathbb{R}^3} f_\varepsilon(t, x, v) \left| v - \frac{\langle j_{f_\varepsilon}(t) \rangle}{\langle \rho_{f_\varepsilon} \rangle} \right|^2 dv dx + \frac{1}{2} \int_{\mathbb{T}^3} |u_\varepsilon(t, x) - \langle u_\varepsilon(t) \rangle|^2 dx + \frac{\langle \rho_{f_\varepsilon} \rangle}{2(1 + \langle \rho_{f_\varepsilon} \rangle)} \left| \frac{\langle j_{f_\varepsilon}(t) \rangle}{\langle \rho_{f_\varepsilon} \rangle} - \langle u_\varepsilon(t) \rangle \right|^2.$$

and observe that

$$\frac{d}{dt} \mathcal{E}_\varepsilon(t) + D_\varepsilon(t) = 0,$$

as a consequence of the **energy-dissipation identity** and of the **conservation of global momentum**

$$\frac{d}{dt} \langle u_\varepsilon + j_{f_\varepsilon} \rangle(t) = 0.$$

Conditional decay of the modulated energy

Lemma (Choi, Kwon (2015))

Let $T > 0$ such that

$$\sup_{\varepsilon \in (0,1)} \|\rho_{f_\varepsilon}\|_{L^\infty((0,T) \times \mathbb{T}^3)} \lesssim 1.$$

Then for all $t \in [0, T]$, there is $\lambda, C > 0$ independent of ε such that for all $\varepsilon \in (0, 1)$ and $t \in [0, T]$,

$$\|u_\varepsilon(t) - \langle u_\varepsilon \rangle(t)\|_{L^2(\mathbb{T}^3)}^2 \lesssim \mathcal{E}_\varepsilon(t) \leq Ce^{-\lambda t} \mathcal{E}_\varepsilon(0).$$

- For $\varepsilon = 1$, [Choi, Kwon 2015] deduced a conditional description of the long time behavior of the VNS system.
- In [HK, Moussa, Moyano 2020] the L^∞ control on ρ_f was proved in a close to equilibrium regime. Our strategy for the high friction limit is actually very much inspired by the latter.

The bootstrap argument

- Introduce

$$T_\varepsilon^* = \sup \left\{ T > 0, \int_0^T \|\nabla_x u_\varepsilon(s)\|_{L^\infty(\mathbb{T}^3)} ds \leq \delta \right\}.$$

In the close to equilibrium regime, the aim is to show that $T_\varepsilon^* = +\infty$.

- By **maximal parabolic** estimates for the **Stokes** equation

$$\begin{cases} \partial_t u_\varepsilon - \Delta_x u_\varepsilon + \nabla_x p_\varepsilon = -u_\varepsilon \cdot \nabla_x u_\varepsilon + \frac{1}{\varepsilon} (j_{f_\varepsilon} - \rho_{f_\varepsilon} u_\varepsilon), \\ \operatorname{div}_x u = 0, \end{cases}$$

we get for $r > 3$,

$$\sup_{\varepsilon \in (0,1)} \left(\|\partial_t u_\varepsilon\|_{L^r(0, T_\varepsilon^*; L^r(\mathbb{T}^3))} + \|D_x^2 u_\varepsilon\|_{L^r(0, T_\varepsilon^*; L^r(\mathbb{T}^3))} \right) \lesssim 1.$$

The bootstrap argument

- Introduce

$$T_\varepsilon^* = \sup \left\{ T > 0, \int_0^T \|\nabla_x u_\varepsilon(s)\|_{L^\infty(\mathbb{T}^3)} ds \leq \delta \right\}.$$

In the close to equilibrium regime, the aim is to show that $T_\varepsilon^* = +\infty$.

- By interpolation, for $\alpha \in (0, 1)$,

$$\|\nabla_x u_\varepsilon\|_{L^\infty(\mathbb{T}^3)} \lesssim \|u_\varepsilon - \langle u_\varepsilon \rangle\|_{L^2(\mathbb{T}^3)}^\alpha \|D_x^2 u_\varepsilon\|_{L^r(\mathbb{T}^3)}^{1-\alpha}$$

and we can use the (conditional) exponential decay of the modulated energy :

$$\int_0^{T_\varepsilon^*} \|\nabla_x u_\varepsilon(s)\|_{L^\infty(\mathbb{T}^3)} ds \lesssim \mathcal{E}_\varepsilon(0)^{\alpha/2} \leq \delta/2,$$

for $\mathcal{E}_\varepsilon(0) \ll 1$ (= close to equilibrium), that is

$$\int_{\mathbb{T}^3 \times \mathbb{R}^3} f_{0,\varepsilon} \left| v - \frac{\langle j_{f_{0,\varepsilon}} \rangle}{\langle \rho_{f_{0,\varepsilon}} \rangle} \right|^2 dv dx + \int_{\mathbb{T}^3} |u_{0,\varepsilon} - \langle u_{0,\varepsilon} \rangle|^2 dx + \left| \frac{\langle j_{f_{0,\varepsilon}} \rangle}{\langle \rho_{f_{0,\varepsilon}} \rangle} - \langle u_{0,\varepsilon} \rangle \right|^2 \ll 1.$$

Higher dissipation functionals

- In the maximal parabolic estimates, we need to desingularize the Brinkman force $F_\varepsilon = \frac{1}{\varepsilon} (j_{f_\varepsilon} - \rho_{f_\varepsilon} u_\varepsilon)$.
- **Higher dissipation functional** introduced in [HK, 2022] for the large time behavior of VNS on $\mathbb{R}^3 \times \mathbb{R}^3$:

$$D_\varepsilon^{(r)} = \int_{\mathbb{T}^3 \times \mathbb{R}^3} f_\varepsilon \frac{|v - u_\varepsilon|^r}{\varepsilon^r} dv dx,$$

which is useful, since

$$\|F_\varepsilon\|_{L^r((0,T) \times \mathbb{T}^3)} \leq \|\rho_{f_\varepsilon}\|_{L^\infty(0,T) \times \mathbb{T}^3}^{1-\frac{1}{r}} \left(\int_0^T D_\varepsilon^{(r)} dt \right)^{\frac{1}{r}}.$$

We prove that for $\eta \ll 1$,

$$\begin{aligned} & \int_0^T D_\varepsilon^{(r)} dt + \int_{\mathbb{T}^3 \times \mathbb{R}^3} f_\varepsilon(t) \frac{|v - u_\varepsilon(t)|^r}{\varepsilon^{r-1}} dv dx \\ & \lesssim \|f_{0,\varepsilon}\|_{L^1(\mathbb{R}^3; L^\infty(\mathbb{T}^3))} \|\partial_t u_\varepsilon\|_{L^r((0,T) \times \mathbb{T}^3)}^r \\ & + \eta \|D_x^2 u_\varepsilon\|_{L^r((0,T) \times \mathbb{T}^3)}^r + \int_{\mathbb{T}^3 \times \mathbb{R}^3} f_{0,\varepsilon} \frac{|v - u_{0,\varepsilon}|^r}{\varepsilon^{r-1}} dv dx + 1. \end{aligned}$$

Higher dissipation functionals

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We prove that for $\eta \ll 1$,

$$\begin{aligned} \|\partial_t u_\varepsilon\|_{L^r(0, T_\varepsilon^*; L^r(\mathbb{T}^3))} + \|D_x^2 u_\varepsilon\|_{L^r(0, T_\varepsilon^*; L^r(\mathbb{T}^3))} &\lesssim \\ &\|f_{0,\varepsilon}\|_{L^1(\mathbb{R}^3; L^\infty(\mathbb{T}^3))}^{1/r} \|\partial_t u_\varepsilon\|_{L^r(0, T_\varepsilon^*; L^r(\mathbb{T}^3))} + \eta^{1/r} \|D_x^2 u_\varepsilon\|_{L^r(0, T_\varepsilon^*; L^r(\mathbb{T}^3))} + 1. \end{aligned}$$

Some open questions

- Remove the smallness assumptions ?
- Remove the smoothness assumptions : derivation from Leray solutions of Vlasov-Navier-Stokes to Leray solutions of inhomogeneous Navier-Stokes ?
- Inclusion of the effect of **gravity** : see inertialess limits by [[Höfer 2018](#)] for Vlasov-Stokes and [[Ertzbischoff 2022](#)] for Vlasov-Navier-Stokes on the half-space with absorption condition on the boundary.

Thanks for listening !